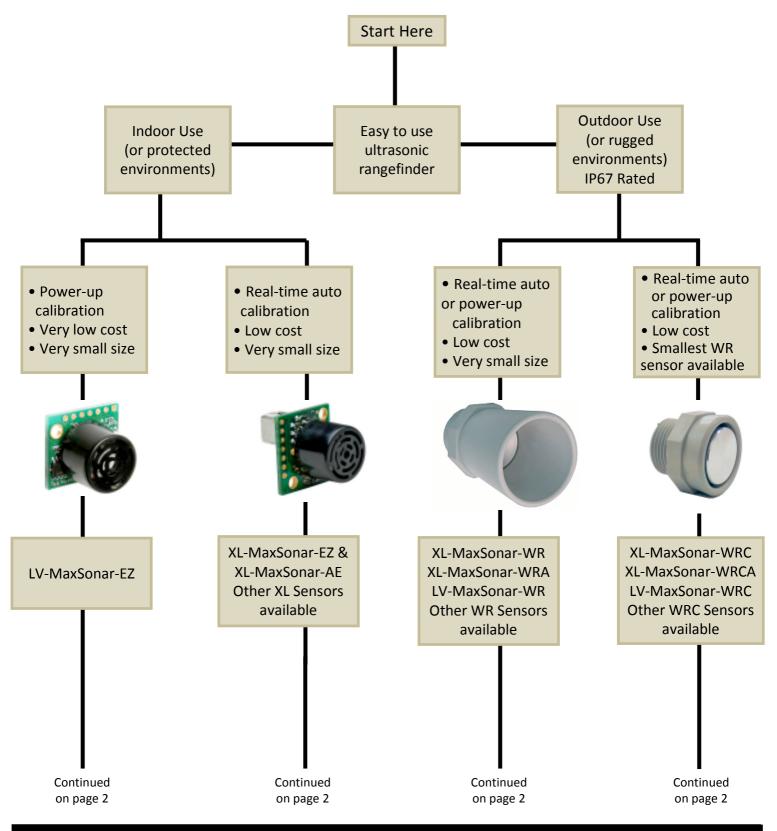
# Choose the Proper Ultrasonic Sensor for your Application

This guide will help you select the correct MaxSonar<sup>®</sup> sensor for your use. We believe that the MaxSonar<sup>®</sup> sensors are among the easiest to use ultrasonic rangefinders available.



### MaxBotix<sup>®</sup> Inc.

The names MaxBotix®, MaxSonar®, EZ0, EZ1, EZ2, E4, AE0, AE1, AE2, AE3, AE4, WR1, and WRC1 are trademarks of MaxBotix Inc.

PD10171d Page 1 Email: <u>info@maxbotix.com</u> Web: <u>www.maxbotix.com</u>

		* · · · · · · · · · · · · · · · · · · ·		•
	LV-MaxSonar-EZ	XL-MaxSonar-EZ	LV-MaxSonar-WR	LV-MaxSonar-WRC
		XL-MaxSonar-AE	XL-MaxSonar-WR XL-MaxSonar-WRA	XL-MaxSonar-WRC XL-MaxSonar-WRCA
				0
Easy to use interface with Trigger or Free-run Operation and Stable				
Range Data	Yes	Yes	Yes	Yes
Range produced by Analog				
Voltage Output and Serial Output	Yes	Yes	Yes	Yes
Ουιραι	Tes			
		Yes-(XL-EZ)	Yes-(XL-WR, LV-WR)	Yes-(XL-WRC, LV-WRC)
Pulse Width Output	Yes	No-(XL-AE)	No-(XL-WRA)	No-(XL-WRCA)
Real-time Analog Envelope Output of the Acoustic		No-(XL-EZ)	No-(XL-WR, LV-WR)	No-(XL-WRC, LV-WRC)
Waveform	No	Yes-(XL-AE)	Yes-(XL-WRA)	Yes-(XL-WRCA)
waveronn			Tes-(AL-WRA)	Tes-(XL-WRCA)
	No	No		
	(can be mounted in a way that protects the sensor from	(can be mounted in a way that protects the sensor from		
IP67 Rated for Outdoor Use	exposure to the elements.)	exposure to the elements.)	Yes	Yes
Automatic Calibration to				
Compensate for Changes				
in Temperature, Voltage,			Yes	Yes
Humidity and Noise.	On power up only	Yes	No- (LV-WR On power up only)	No- (LV-WRC On power up only)
			Yes	Yes
Has noise canceling	Some	Yes	Some- (LV-WR)	Some- (LV-WRC)
			1 cm- (XL-WR, XL-WRA)	1 cm- (XL-WRC, XL-WRCA)
Resolution	1 inch	1 cm	1 inch- (LV-WR)	1 inch- (LV-WRC)
Maximum Rate Readings			10Hz- (XL-WR, XL-WRA)	10Hz- (XL-WRC, XL-WRCA)
are taken	20Hz	10Hz	20Hz- (LV-WR)	20Hz- (LV-WRC)
3.3V Operation, Average	20112	10112		
Current Draw	1.6mA	2.1mA	2.1mA	2.1mA
5V Operation, Average				
Current Draw	1.9mA	3.4mA	3.4mA	3.4mA
Acoustic Frequency	42kHz	42kHz	42kHz	42kHz
Minimum Object Detection				
Distance <sup>(2)</sup>	0 inches	0 cm <sup>(1)</sup>	0 cm/inches	3 cm/inches
Minimum Reported			20 cm- (XL-WR, XL-WRA)	20 cm- (XL-WRC, XL-WRCA)
Distance <sup>(2)</sup>	6 inches	20 cm	12 inches- (LV-WR)	12 inches- (LV-WRC)
		765 cm <sup>(3)</sup>	765 cm <sup>(3)</sup> - (XL-WR, XL-WRA)	645 cm <sup>(5)</sup> - (XL-WRC, XL-WRCA)
	254 inches			
Maximum Range	(6.45 meters)	(25.1 feet)	254 inches- (LV-WR)	254 inches- (LV-WRC)
Semi-custom solution				
available to meet almost	Yes <sup>(4)</sup>	Yes <sup>(4)</sup>	Yes <sup>(4)</sup>	Yes <sup>(4)</sup>
any need	res' '	res' '	res' '	Yes' '

Product Line

Ultrasonic Sensor Selection Guide

Note 1: Objects from 0-mm to 1-mm may not be detected.

Note 2: Objects closer than the minimum-distance-reported\*, typically range as this value\*.

Note 3: Sensors with a 1068cm maximum range are available.

Note 4: Contact MaxBotix Inc., to have your sensor solution evaluated.

Note 5: Sensors may intermittently detect large objects out 765cm. The maximum reported range is 765cm.

Continued	Continued	Continued	
on page 3	on page 3	on page 3	

Continued on page 3

## MaxBotix<sup>®</sup> Inc.

The names MaxBotix®, MaxSonar®, EZ0, EZ1, EZ2, E4, AE0, AE1, AE2, AE3, AE4, WR1, and WRC1 are trademarks of MaxBotix Inc.

PD10171d Page 2 Email: <u>info@maxbotix.com</u> Web: <u>www.maxbotix.com</u>

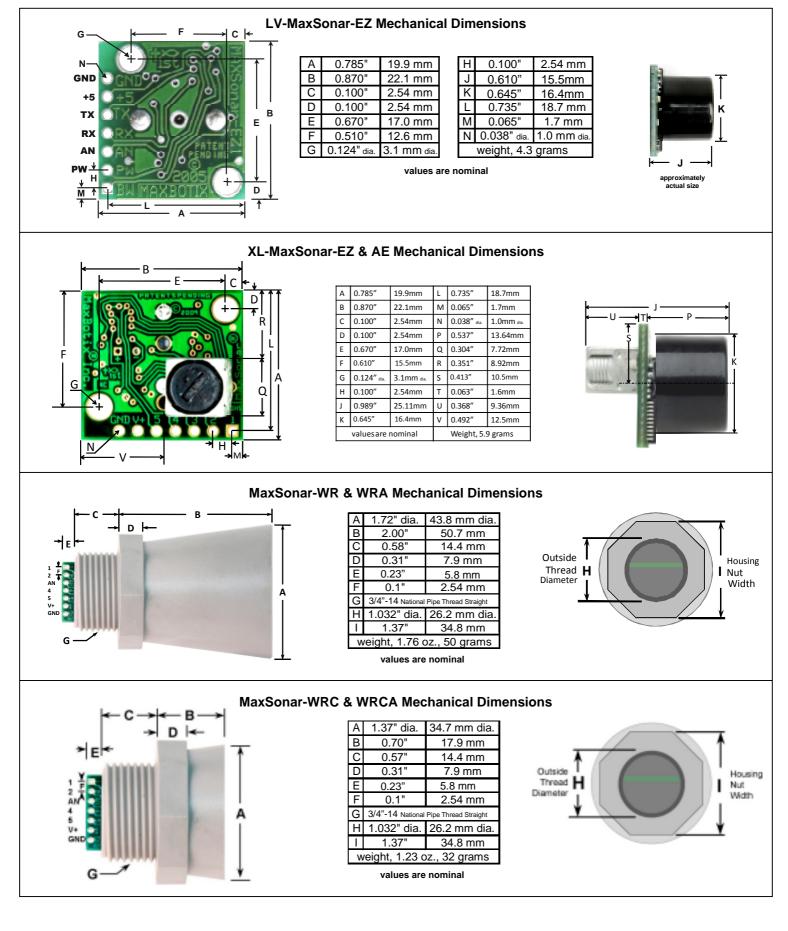
#### Ultrasonic Sensor Selection Guide

LV-MaxSonar-EZ Some Features: • Easy to use interface • 1 inch resolution • Various calibrated beam widths • Size is less than 1 cubic inch Possible Applications: • Educational and hobby robots • Distance measuring • UAV • Some industrial uses* • Autonomous navigation Comments: • Power up calibration compensates for various mounting arrangements and environments. • For best operation, must be clear of objects for 14 inches during power up calibration. • NOTE: Requires user to cycle the power to recalibrate sensor if the voltage, temperature or humidity change during operation.	XL-MaxSonar-AE Some Features: • Easy to use interface • 1 cm resolution • Various calibrated beam widths • Size is less than 1 cubic inch • Real-time auto calibration • Real-time noise rejection • High acoustic power FOR THE ANALOG ENVELOPE (AE) • Real-time analog envelope Possible Applications: • Robots • Distance measuring • UAV • Industrial uses • Autonomous navigation • Bin levels • Changing environment conditions FOR THE ANALOG ENVELOPE (AE) • Troubleshooting and sensor integration • User signal processing • recommended for sensor integration process into systems Comments: • Automatically compensates for noisy and changing environmental conditions (temperature, voltage or humidity). • Auto calibration will compensate for and detect up close objects. FOR THE ANALOG ENVELOPE (AE) • Allows easy identification of troubleshooting issues using the real-time analog envelope.	LV-MaxSonar-WR XL-MaxSonar-WRA Some Features: • Easy to use interface • IP67 rated • 1 cm (or 1 inch LV-WR) resolution • Calibrated beam width • Small size • High acoustic power FOR THE WRA (ANALOG ENVELOPE) • Real-time analog envelope Possible Applications: • Robots • Distance measuring • Industrial uses • UAV • Autonomous navigation • Bin levels • Changing environment conditions • Tank levels • Proximity zone detection FOR THE WRA (ANALOG ENVELOPE) • Troubleshooting and sensor integration • User signal processing • recommended for sensor integration process into systems • Auto calibration will compensate for and detect up close objects. • 10 meter part detect larger targets to the long 10 meter range FOR THE WRA (ANALOG ENVELOPE) • allows easy identification of troubleshooting issues using the real-time analog	LV-MaxSonar-WRC XL-MaxSonar-WRCA Some Features: •Easy to use interface •Smallest compact IP67 rated size available •1 cm (or 1 inch LV-WRC) resolution •Calibrated beam width •Real-time auto calibration •Real-time noise rejection •High acoustic power FOR THE WRCA (ANALOG ENVELOPE) •Real-time analog envelope Possible Applications: •Robots •Distance measuring •Industrial uses •UAV •Autonomous navigation •Bin levels •Changing environment conditions •Tank levels •Proximity zone detection FOR THE WRCA (ANALOG ENVELOPE) •Troubleshooting and sensor integration • User signal processing • recommended for sensor integration process into systems Comments: •Automatically compensates for noisy and changing environmental conditions (temperature, voltage or humidity). •Auto calibration will compensate for and detect up close objects. FOR THE WRCA (ANALOG ENVELOPE) •allows easy identification of troubleshooting issues using the real-time analog
Continued	Continued	Continued	Continued
on page 4	on page 4	on page 4	on page 4

## MaxBotix<sup>®</sup> Inc.

The names MaxBotix®, MaxSonar®, EZ0, EZ1, EZ2, E4, AE0, AE1, AE2, AE3, AE4, WR1, and WRC1 are trademarks of MaxBotix Inc.

PD10171d Page 3 Email: <u>info@maxbotix.com</u> Web: <u>www.maxbotix.com</u>



### MaxBotix<sup>®</sup> Inc.

The names MaxBotix®, MaxSonar®, EZ0, EZ1, EZ2, E4, AE0, AE1, AE2, AE3, AE4, WR1, and WRC1 are trademarks of MaxBotix Inc.